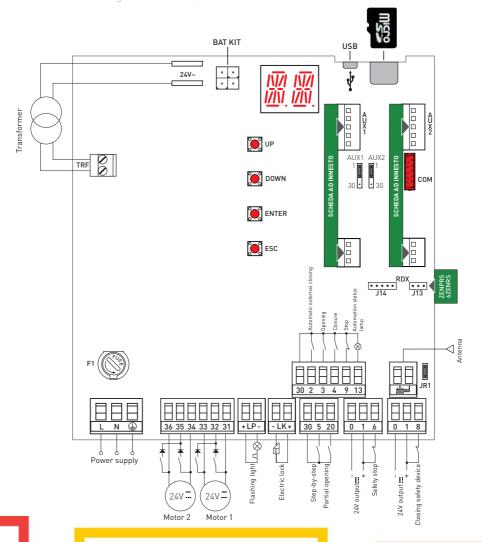


IP2246EN • 2018-03-23

Entrematic LCU40H 1 HomeLink.



Control panel installation manual for automations with one or two 24V motors -



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Key



This symbol indicates instructions or notes regarding safety, to which special attention must be paid.



This symbol indicates useful information for the correct functioning of the product.

Factory settings

1. General safety precautions



Failure to observe the information given in this manual may lead to personal injury or damage to the equipment.

Keep these instructions for future reference

This installation manual is intended for qualified personnel only.

Installation, electrical connections and adjustments must be performed in accordance with Good Working Methods and in compliance with the present standards.

This product must only be used for the specific purpose for which it was designed.

Any other use is to be considered improper and therefore dangerous. The manufacturer cannot be held responsible for any damage caused by improper, incorrect or unreasonable use.

Read the instructions carefully before installing the product. Incorrect installation could be dangerous.

A The packaging materials (plastic, polystyrene, etc.) should not be discarded in the environment or left within reach of children, as they are a potential source of danger.

Before installing the product, make sure it is in perfect condition.

Do not install the product in explosive areas and atmospheres: the presence of inflammable gas or fumes represents a serious safety hazard.



The safety devices (photocells, safety edges, emergency stops, etc.) must be installed taking into account the applicable laws and directives, Good Working

Methods, installation premises, system operating logic and the forces developed by the automation

Before connecting the power supply, make sure the plate data correspond to those of the mains power supply. An omnipolar disconnection switch with a contact opening distance of at least 3 mm must be fitted on the mains supply.

Check that there is an adequate residual current circuit breaker and a suitable overcurrent cut-out upstream of the electrical installation in accordance with Good Working Methods and with the laws in force.

When requested, connect the automation to an effective earthing system that complies with current safety standards.



During installation, maintenance and repair operations, cut off the power supply Lessenge before opening the cover to access the electrical parts.

The electronic parts must be handled using earthed antistatic conductive arms. The manufacturer of the motorisation device declines all responsibility if component parts not compatible with safe and correct operation are fitted.

Only use original spare parts when repairing or replacing products.

1.1 Safety functions

The Entrematic LCU40H control panel has the following safety functions:

- obstacle recognition with force limiting;

The maximum response time of the safety functions is $0.5 \, s$. The reaction time to a faulty safety function is $0.5 \, s$.

The safety functions comply with the standards and performance level indicated below:

EN ISO 13849-1:2015 Category 2 PL=c EN ISO 13849-2:2012

The safety function cannot be bypassed either temporarily or automatically. Fault exclusion has not been applied.

2. EC Declaration of Conformity

Entrematic Group AB declares that the Entrematic LCU40H control panel complies with the fundamental requisites and other relevant requirements laid down by the following EC directives: EMC Directive 2014/30/EU:

Low Voltage Directive 2014/35/EU;

RED Directive 2014/53/EU.

Landskrona, 01-07-2016

Matteo Fino

3. Technical specifications

	LCU40H	LCU40HJ		
Power supply	230 V~ 50/60 Hz	120 V~ 50/60 Hz		
Power absorption	0,6 A	1,2 A		
Fuse	F2 A	4 A		
Motor output	24 V = 12 A max (X 2)			
Permanent power supply to accessories 0-30	24 V = 0,15 A			
Power supply to accessories 0-1 (in any case, the total of accessories 0-30 and 0-1 must not exceed $0.5A$).	24 V = 0,5 A continuous			
Ambient temperature	-20 °C - +55 °C			
Storable radio codes	100 / 200 see RO \rightarrow MU \rightarrow 20/10 (paragraph 11.6)			
Radio frequency	433,92 MHz			
Degree of protection of the container	IP55			
Product size	238 x 357 x 120			
Operating cycles	Refer to the characteristics of the actuator used.			



NB: the given operating and performance features can only be guaranteed with the use of DITEC Entrematic accessories and safety devices.

3.1 Applications











4. Installation and electrical connections

- Perforate the relevant points in the bottom part of the box (Fig. 4.1).
- Fix the control panel firmly in place. You are advised to use convex head screws (max head Ø 10mm) with a cross imprint (the centre distance for the holes is shown in Fig. 4.2).
- Insert the cable glands and corrugated tubes from the lower side of the container.
- Before connecting the power supply, make sure the plate data correspond to those of the mains power supply.
- An omnipolar disconnection switch with a contact opening distance of at least 3mm must be fitted on the mains supply.
- Check there is an adequate residual current circuit breaker and overcurrent cut-out upstream of the electrical system.
- For the power supply, use a H05RN-F 3G1.5 type electric cable. Connect it to the terminals L (brown), N (blue), ((yellow/green) inside the automation (Fig. 4.3, page 6).

NB: the maximum permitted wire section is AWG14 (2mm²).

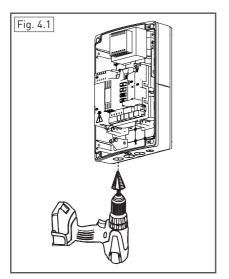
- Unsheathe the part of the power supply cable in line with the terminal, and use a cable fastener to hold it in place [A].
- In order to comply with the essential requisites of the Standards in force, reclose the cover once the wires have been connected to the terminal.

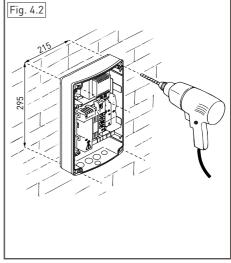


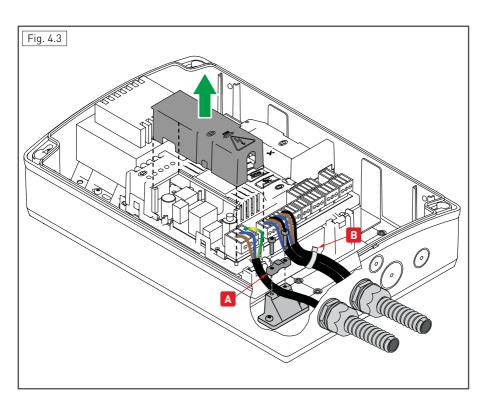
The connections to the mains power supply and to any possible low voltage wires [230V] in the section outside the control panel must be made on an independent channel separated from the connections to the command and safety devices (SELV = Safety Extra Low Voltage). The corrugated tubes must enter the control panel by a few centimetres via the holes on the base box.

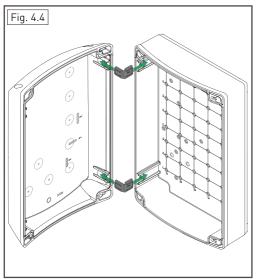
- Make sure there are no sharp edges that may damage the cables.
- Make sure the mains power wires (230V) and the accessory wires (24V) are separated.
- The cables must have dual insulation, be sheathed near the relative connection terminals, and be held in place with ties [B] (not supplied).
- If necessary, fit the clip hinges on the bottom of the box and on the cover (left or right side, as preferred) (Fig. 4.4, page 6).

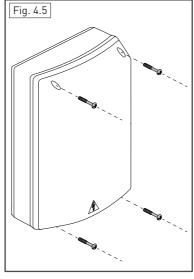
After making the adjustments and settings, fix the cover in place with the screws supplied (Fig. 4.5, page 6).









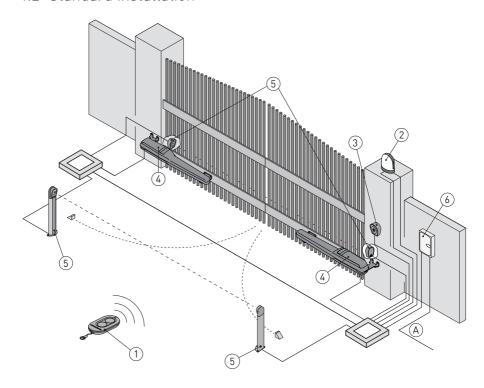


4.1 Maintenance

The control panel needs no special maintenance.

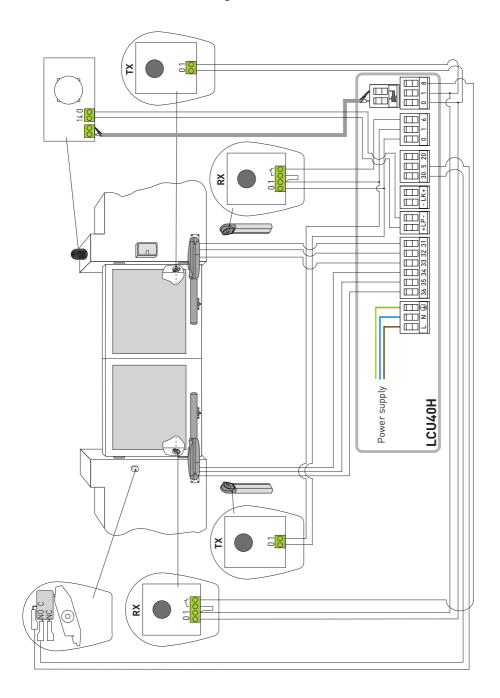
Make regular checks to ensure the good condition of the box seals and the electrical connections.

4.2 Standard installation



Ref.	Description	Cable
1	Transmitter	/
2	Flashing light	2 x 1mm ²
2	Antenna (integrated in the flashing light)	coaxial 50 Ω
3	Key selector switch	4 x 0.5mm ²
3	Digital combination wireless keypad	/
,	Actuator	2 x 1.5mm ²
4	Actuator with limit switch	3 x 1.5mm²
5	Photocells	4 x 0.5mm ²
6	Control panel	3G x 1.5mm ²
Α	Connect the power supply to a type-approved omnipolar switch, with a contact opening distance of at least 3mm (not supplied). Connection to the mains must be via an independent channel, separated from the separated separated and sofety devices.	

4.3 Standard installation diagram



5. Programming



NB: pressure on the keys may be quick (less than 2 s) or prolonged (longer than 2 s). Unless specified otherwise, quick pressure is intended. To confirm the setting of a parameter, prolonged pressing is necessary.

5.1 Switching the display ON and OFF

The procedure to switch on the display is as follows:



- press the ENTER key ENTER
- the display functioning check starts



• the first level menu is displayed

The procedure to switch off the display is as follows:

• press the ESC key ESC

NB: the display switches off automatically after 60 s of inactivity.

5.2 Navigation keys

• The simultaneous pressing of the \uparrow and ENTER keys produces an opening command.



 \bullet The simultaneous pressing of the $\mbox{$\downarrow$}$ and ENTER keys produces a closing command.



ullet The simultaneous pressing of the ullet and ullet keys produces a POWER RESET command (power supply interruption and automation restart).









- Keep the UP \uparrow or DOWN \downarrow key pressed to begin fast menu scrolling.
- In some menus, the parameter measurement unit can be viewed by pressing the ENTER key once the value has been displayed.

Example: setting of 10 seconds for parameter OB.











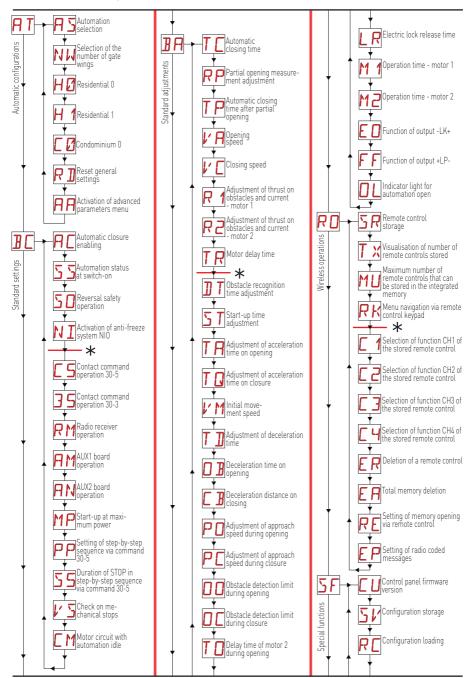


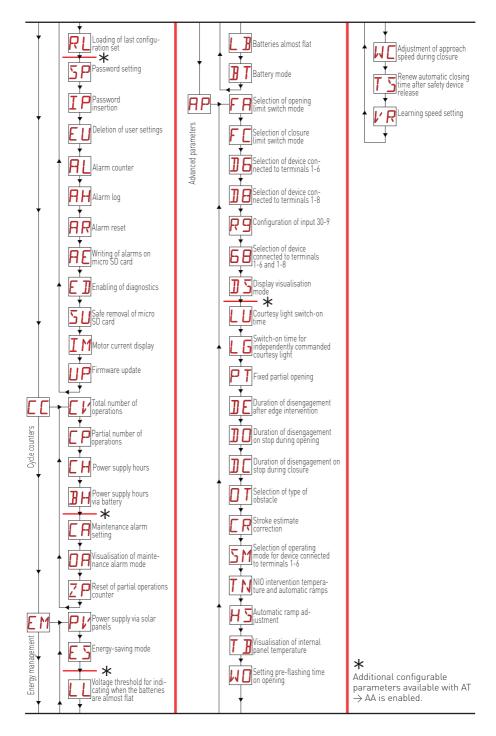






5.3 Menu map





6. Quick start-up sequences

6.1 Selection of automation type

Example of Obbi automation selection

Set



Example of PWR25 automation selection

Set



NB: if no automation is selected (alarm MQ active) using the keys, you can access the values of parameter keys directly.

6.2 Configuration of the number of gate wings

Configuration example for a single gate wing

Set



6.3 Enabling the configurations

Step-by-step mode without automatic closure (residential use)

Step-by-step mode with automatic closure 1 min (residential use) [standard settings]

Opening mode with automatic closure 1 min (condominium use)

6.4 Adding remote controls





6.5 Configuration of the limit switches

Example 1 - Door wing stops against mechanical end stops (standard setting)
Set

Example 2 - Door wing stops against limit switches

Set

With these settings, if an obstacle is detected while the gate wing is opening, it stops with a disengagement operation; during closure, the gate wing reopens).

Example 3 - Door wing stops against mechanical end stops and reverses motion if an obstacle is detected

Set

With these settings, the gate wing stops against its respective mechanical closing end stop and the opening limit switch.

If an obstacle is detected during the opening and before the activation of the stop limit switch, the gate wing stops with a disengagement operation.

If an obstacle is detected during closure and before the activation of the proximity limit switch, the gate wing reopens; once the proximity limit switch has been activated, the gate wing stops against the obstacle.

6.6 Configuration of the safety devices

Example 1 - Configuration of the photocells connected to terminals 1-8 and 1-6 [standard settings]
Set

Example 2 - Configuration of the safety edge with safety test simultaneously connected to terminals 1-6 and 1-8

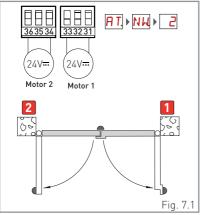
Set

WARNING: Ensure that the forces exerted by the door wings are compliant with EN12453-EN12445 regulations.

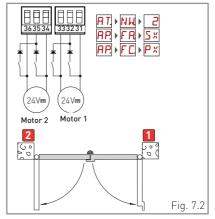
7.1 Automations with two swinging gates



When the Entrematic LCU40H control panel is used in applications for automations with two overlapping swinging gate wings, the following connections can be made:



(Fig. 7.1) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.

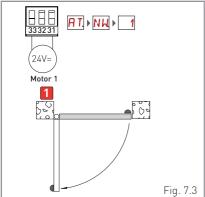


(Fig. 7.2) Installation with mechanical end stop for closure, and with the use of electric limit switches (stop during opening and proximity during closure).

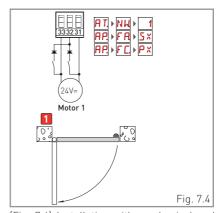
7.2 Automations with one swinging gate wing



When the Entrematic LCU40H control panel is used in applications for automations with one swinging gate wing, the following connections can be made:



(Fig. 7.3) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.

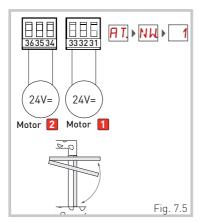


(Fig. 7.4) Installation with mechanical end stop for closure, and with the use of electric limit switches (stop during opening and proximity during closure).

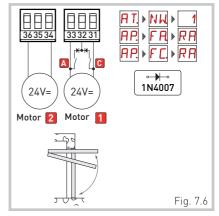
7.3 Up-and-over doors with two parallel motors



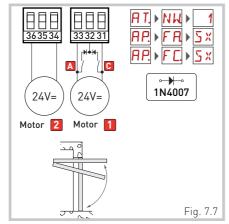
When the Entrematic LCU40H control panel is used in applications for automations with up-and-over doors with two parallel motors, the following connections can be made:



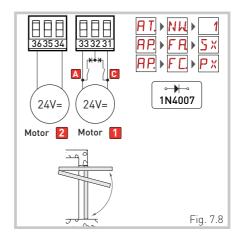
(Fig. 7.5) Installation with mechanical end stops for opening and closure, and without the use of electric limit switches.



[Fig. 7.6] Installation with electric limit switches for deceleration during opening and closure.



[Fig. 7.7] Installation with electric limit switches (stop during opening and closure).



[Fig. 7.8] Installation with electric limit switches (stop during opening and proximity during closure).

8. Commands



You are advised to read paragraph 11 for all the details about the possible adjustments.



WARNING: terminal 30 (common positive for commands) has the same functions as terminal 1, so the commands visible on the display are indicated with 1-5, 1-3, 1-4, etc. It is different from terminal 1, however, because of the maximum current that can be dispensed and it is also active when the control panel is in standby $\mathbf{E} \ \mathbf{S} \Rightarrow \mathbf{D} \ \mathbf{N}$.

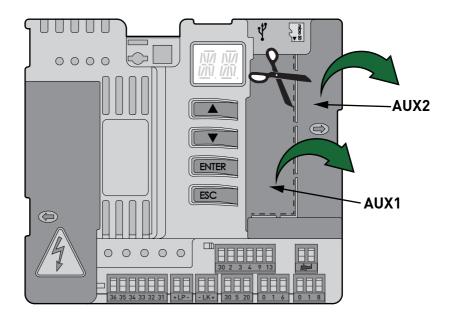
	Command		Function	Description
30 -	2	NO	AUTOMATIC CLOSURE	The permanent closure of the contact enables automatic closure if $\mathbf{AC} \to \mathbf{I} \cdot \mathbf{C}$
			OPENING	When selecting $\P \ $
30 -	3	NO	STEP-BY-STEP	When selecting $3 \rightarrow 3 \rightarrow 1-5$, the closure of the contact activates a sequential opening or closing operation: opening-stop-closing-opening" sequence can be changed to "opening-stop-closing-stop-opening" by selecting $3 \leftarrow PP$.
30 -	4	NO	CLOSURE	The closure of the contact activates a closing operation.
30 -	5	NO	STEP-BY-STEP	When selecting $\ref{MC} \rightarrow \ref{L} \rightarrow \ref$
			OPENING	When selecting $\P \cap \subseteq \subseteq S \rightarrow I$, the closure of the contact activates an opening operation.
1 —		NC	SAFETY STOP	The opening of the safety contact stops and prevents any movement. NB: \PPSM to set different safety contact functions, see the \rightarrow parameter settings.
1 —		NC	CLOSING SAFETY DE- VICE	The opening of the safety contact triggers a reversal of the movement (reopening) during the closing operation. When selecting $\mathbb{F} \cap \mathcal{F} \cap \mathcal{F} \cap \mathcal{F}$, the opening of the contact prevents any operation when the automation is idle. When selecting $\mathbb{F} \cap \mathcal{F} \cap \mathcal{F} \cap \mathcal{F}$, the opening of the contact only prevents closure when the automation is idle.
1 —	6 8	NC	CLOSING/ OPENING SAFETY DE- VICE	The opening of the safety contact stops and prevents any movement. NB: operation corresponds to that of contact 1-6 with $\Pi P \to SM \to 0.5$.
30 -		NC	STOP	The opening of the safety contact causes the current operation to stop. If $\Pi P - R G = G P$, automatic closure is disabled when contact 30-9 recloses. If $\Pi P - R G = G P$, automatic closure remains enabled when contact 30-9 recloses.
30 -	9	NO	"OPERATOR PRESENT" COMMAND	When selecting $\Pi P \rightarrow R G \rightarrow HR$, the opening of contact 30-9 enables the "operator present" function: - opening with operator present 30-3 - closure with operator present 30-4 NB: any safety devices, automatic closure and plug-in board in the AUX housing are all disabled.
30 —	20	N0	PARTIAL OPEN- ING	The closure of the contact activates a partial opening operation. Once the automation stops, the partial opening control performs the opposite operation to the one performed before the stop.



WARNING: make a jumper for all NC contacts if not used, or deactivate them via the relative menu. Terminals with the same number are equal.

To access the slots for plug-in boards (AUX):

- If you want to insert just one board, cut the control panel cover and remove it as shown in the figure.
- If both slots are needed, remove the cover completely.



8.2 SOFA1-SOFA2 or GOPAVRS self-controlled safety edge

Command		Function	Description
SOFA1-SOFA2 GOPAV		SAFETY TEST	Insert the SOFA1-SOFA2 or GOPAVRS device in the slot for plug-in boards AUX1 or AUX2. If the test fails, an alarm message appears on the display.
1 — 6	NC	SAFETY STOP	When selecting $\PP \to \ref{1}6 \to \ref{2}4$, connect the output contact of the safety device to terminals 1-6 on the control panel (in series with the photocell output contact, if installed).
1 — 1 8	NC	CLOSING SAFE- TY DEVICE	When selecting $\PP \to \ref{1}B \to \ref{2}H$, connect the output contact of the safety device to terminals 1-8 on the control panel (in series with the photocell output contact, if installed).
1 6 8	NC	CLOSING/ OPENING SAFETY DEVICE	When selecting $P \rightarrow P $

9. Outputs and accessories

Output	Value of accessories	Description
0 1	24V / 0.5 A	Power supply to accessories Output for power supply to external accessories. NB: the maximum absorption of 0.3A corresponds to the sum of all terminals 1. The "gate open" indicator light (30-13) is not calculated in the 0.3A indicated above. The maximum value to be considered is 3W.
	GOL148REA	If the GOL868R4 radio receiver is used (868.35 MHz), connect the supplied antenna wire (90mm).
+LP-	LAMPH 24V / 25W	Flashing light The pre-flashing settings can be selected from the third level menu $\mathbb{RP} \to \mathbb{W}$ and/or $\mathbb{RP} \to \mathbb{W}$. To modify the operating mode of the LP output, refer to the selection $\mathbb{RP} \to \mathbb{F}$.
30 2 3 4 9 13	≔ 24√ / 3W	Automation status lamp For the operating mode of output 30-13, refer to the selection $\Box \Box \Box \Box \Box \Box \Box$.
- LK+	12V~ / 15W	Electric lock It is activated when the operation begins with the automation closed. To modify the operating mode of the LK output, refer to the selection $\P \cap P \to C$.
AUX 1 AUX 2	SOFA1-SOFA2 GOPAVRS LAN4S LAB9 BIXLR12 BIXLR22 GOL868R4 BIXLR42 LAN7S	The control panel has two slots for plug-in command and safety boards. The action of the control board can be selected using $\ref{eq:control} \hookrightarrow \ref{eq:control} \hookrightarrow eq:cont$
RDX	6ZENRS ZENPRS	The control panel is fitted with a housing for modules of the 6ZENRS radio receiver type [433.92 MHz]. Can be replaced with a radio receiver module of the ZENPRS type [868.35 MHz]. The operating mode is selected via $\Box \Box \Box \rightarrow RM$. When using slot-in radio boards, remove the RDX module. The display will show RV . WARNING: the modules must be inserted and removed with the power supply disconnected.

Output	Value of accessories	Description
ψ	USB	The control panel is fitted with a USB input for connecting to a PC in order to update firmware files using AMIGO software (with a Standard-A plug, or Micro-B plug USB cable).
Migg	MicroSD	The control panel manages microSD cards for updating the firmware and for diagnostics and configuration storage/recovery via the in commands $\mathbf{SF} \to \mathbf{SV}$ and $\mathbf{SF} \to \mathbf{RC}$. NB: use a microSD with a maximum capacity no greater than 16 Gb.
С <u>о</u> м		COM - This allows the functioning configurations to be saved using the function $\Sigma F \to \Sigma V$. The saved configurations can be recalled using the function $\Sigma F \to RC$.
	BIXM R2	COM - The storage module allows the remote controls to be stored. If the control panel is replaced, the storage module being used can be inserted in the new control panel. WARNING: the storage module must be inserted and removed with the power supply disconnected, and paying attention to the positioning direction.
BAT	SBU	BAT - Battery-powered operation. The batteries are kept charged when the power supply is on. If the power supply is off, the panel is powered by the batteries until the power is re-establish or until the battery voltage drops below the safety threshold. The panel turns off in the last case. WARNING: the batteries must always be connected to the control panel for charging. Periodically check the efficiency of the batteries. NB: the operating temperature of the rechargeable batteries is from +5°C to +40°C. For advanced control of battery-powered operation, refer to the menu [M.

10. Jumper setting

Jumper	Description	0FF	ON
JR1	Display mode selection	Display mode. Only the values and parameters present can be displayed.	Maintenance mode. Only the values and parameters present can be displayed and modified. Activated maintenance mode is indicated by the permanent switching on of the right-hand point on the display.

Jumper	Description	1 30	1 30
AUX1	Selection of power supply - auxiliary board 1	AUX1 powered from 0-1.	AUX1 powered from 0-30.
AUX2	Selection of power supply - auxiliary board 2	AUX2 powered from 0-1.	AUX2 powered from 0-30.

11. Adjustments



NB: depending on the type of automation and control panel, some menus may not be available.

11.1 Main menu

Display	Description
AT	AT - Automatic Configurations. The menu allows you to manage the automatic configurations of the control panel.
36	BC - Basic Configurations. The menu allows you to display and modify the main settings of the control panel.
BA	BA - Basic Adjustments. The menu allows you to display and modify the main adjustments of the control panel. NB: some settings require at least three operations before they are set correctly.
RO	RO - Radio Operations. The menu is used to manage the radio functions of the control panel (alarm management, diagnostics enabling, FW updating).
5F	SF - Special Functions. The menu allows you to set the password and manage the special functions in the control panel.
	CC - Cycles Counter. The menu allows you to display the number of operations carried out by the automation and manage the maintenance interventions.
EM	EM - Energy Management. The menu allows you to display and modify the energy saving settings and adjustments (Green Mode and battery management).
RP	AP - Advanced Parameters. The menu allows you to display and modify the advanced settings and adjustments of the control panel (limit switch mode, selection of devices connected to the terminals, disengagement duration adjustments, flashing light adjustments, etc.).
	NB: some settings require at least three operations before they are set correctly.

From the main menu you can access the second level menu as follows:

- use the and keys to select the required function
- press ENTER to confirm

After confirming the selection, you access the second level menu.

For each function of the main menu, there are also additional configurations that can be viewed by enabling the \mathbf{H} function (see the following paragraph).



 $\ensuremath{\mathsf{NB}}$: to check if the parameters have actually been modified, quit the relative parameter and then access it again.

The modifications will take effect from the next operation.

11.2 Second level menu - AT (Automatic Configurations)

	Display	Display Description						
	A 2	AS - Automation selection This selection pre-sets the type of motor and a sub-set of parameters linked to the kinematic mechanism of the automation for a standard installation. See "Selection of automation type", paragraph 11.3. Each parameter can still be modified when necessary.	<u>NO</u> 17					
	1111	NW - Selection of the number of gate wings In the case of automations with a single gate wing, connect motor 1.	0102					
AT - Automatic configurations	HØ	KM - remote control operation : step	o-by-step o-by-step o-by-step					
	<u>H 1</u>	RM - remote control operation : step	bled inute o-by-step o-by-step o-by-step					
		CO - Predefined setting, condominium use 0 This selection loads predefined values for certain standard parame AC - Enabling of automatic closure : enabled TC - setting of automatic closing time : 1 minute C5 - step-by-step/opening command operation : Opening RM - remote control operation : Opening AM - AUX plug-in board operation : Opening SS - Selection of automation status at start-up : closed	ters:					
	Rl	RD - Resetting of general settings (SETTINGS RESET) $ \begin{array}{c} $						
	AA	AA - Activation of additional configurable parameters for each function of the main menu.	1888					

11.2.1 Selection of automation type $\overrightarrow{A} \xrightarrow{\Gamma} \rightarrow \overrightarrow{A} \xrightarrow{\Sigma}$ and specific default settings

	Model	_	D4 D0	VA VO	MD	DO DO	T.4	TO	1/14
AS Type of automa- tion	Modet	CM Motor circuit	R1-R2 Thrust on obsta- cles and current	VA - VC Speed during opening and closure	VR Learn- ing speed	Ap- proach speed	Accel- eration time during opening	Acceleration time during closure	VM Ramp start-up speed
01	OBBI3BH		50	24	18	07	2	3	03
02	ARCBH	CL	70	14	10	06	2	3	03
03	FACIL3H	CL	50	12	10	05	2	3	03
04	LUX03BH-4BH		40	16	12	06	1	2	10
05	LUX05BH- 5VBH (gate wing < 300 Kg or 3,5 m)	0P	40	15	10	06	1	2	10
05	LUXO5BH- 5VBH (gate wing > 300 Kg or 3,5 m)	UP	50	12	08	05	1	2	10
רם	ARC1BH (gate wing < 250 Kg & 3 m)		50	08	06	05	2	3	03
08	ARC1BH (gate wing > 250 Kg or 3 m)		60	06	05	04	2	3	03
09	DOR1BH-1BHS (gate wing < 300 Kg or 1+1 m)	CL	50	08	06	05	2	4	03
10	DOR1BH-1BHS (gate wing > 300 Kg or 1+1 m)		60	06	05	04	3	6	02
11	CUBIC6H-6HV- 30H		60	12	08	06	2	3	05
12	B0X3SH		50	10	06	05	1	5	03
13	DOKE	0P	50	15	08	05	1	1	03
14	PWR25H	01	50	18	10	05	2	3	03
15	PWR35H	CL	50	20	12	06	2	3	03
15	PWR50H (gate wing < 300 Kg or 3,5 m)	0P	40	15	10	06	1	2	10
17	PWR50H (gate wing > 300 Kg or 3,5 m)	UP	50	12	8	05	1	2	10

11.3 Second level menu - BC (Basic Configurations)

	Display	Description	Selections available
Basic configurations	AC	AC - Enabling of automatic closure ON - Enabled 1-2 - Dependent on input 30-2	<u> </u>
	55	SS - Selection of automation status at start OP - Open CL - Closed Indicates how the control panel considers the automation at the time of switch-on, or after a POWER RESET command.	OPCL
	50	SO - Enabling of reversal safety contact functioning ON - Enabled OF - Disabled When enabled (ON) with the automation idle, if the contact 1-8 is operations are prevented. When disabled (OF) with the automation idle, if the contact 1-8 is oper operations are permitted.	
BC -	ΝI	NI - Enabling of NIO electronic anti-freeze system ON - Enabled OF - Disabled When enabled (ON), it maintains the efficiency of the motor even at ent temperatures. NB: for correct operation, the control panel must be exposed to the bient temperature as the motors. The intervention temperature for NIO can be set by selecting PP >	same am-

11.3.1 Additional BC level parameters that can be configured (available with $\Pi \uparrow \rightarrow \Pi \Pi$ enabled)

BC	Display	Description	Selections available
	E 5	C5 - Operation of command associated with contact 30-5 1-5 - Step-by-step 1-3 - Opening	1-51-3
	35	35 - Operation of command associated with contact 30-3 1-5 - Step-by-step 1-3 - Opening	1-31-5
	RM	RM - Radio receiver operation 1-5 - Step-by-step 1-3 - Opening	1-51-3
	AM	AM - Operation of AUX1 plug-in control board 1-5 - Step-by-step 1-3 - Opening	1-51-3
	AN	AN - Operation of AUX2 plug-in control board 1-5 - Step-by-step 1-3 - Opening	1-51-3
	MP	MP - Start-up at maximum power ON - During start-up it increases the thrust on obstacles to maximum OFF-Duringstart-up,thethrustonobstaclesisattheleveladjustedby	<u>ON</u> OF

11.4 Second level menu - BA (Basic Adjustment)

	Display	Description	Selections available
BA - Basic adjustment	TE	TC - Setting of automatic closing time [s] It is set with different intervals of sensitivity. • from 0" to 59" with intervals of 1 second • from 1' to 2' with intervals of 10 seconds	00,59 11,21
	RP	RP - Adjustment of partial opening measurement [%] Adjusts the percentage of operation in relation to the total opening of the automation. Partial opening is performed on gate wing 1. 10 - Minimum 99 - Maximum	10,99
	TP	TP - Setting of automatic closing time after partial opening [s] It is set with different intervals of sensitivity. • from 0" to 59" with intervals of 1 second • from 1' to 2' with intervals of 10 seconds.	00,59 11,21
	ľΑ	VA - Opening speed [V] NB: MAX = 20 for: LUX05BH ARC1BH DOR1BH CUBIC6H-30H BOX3SH DOKE POWER 50H	See paragraph 11.2.1

	Display	Description	Selections available
BA - Basic adjustment	ľE	VC - Closing speed [V] NB: MAX = 20 for: LUX05BH ARC1BH DOR1BH CUBIC6H-30H B0X3SH D0KE POWER 50H	5 4 2 7 See paragraph 11.2.1
	R 1	R1 - Adjustment of thrust on obstacles and current - motor 1 [%] The control panel is fitted with a safety device which, when it detects an obstacle: - stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with $\PP \to \mathbb{JE}$: - reverses the movement during closure operations outside the limit area for detecting obstacles; - stops the movement during closure operations within the limit area for detecting obstacles. The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined on the basis of the selections $\mathbb{J} P \to \mathbb{U}$ 00 - Minimum thrust	G G See paragraph 11.2.1
	R 2	R2 - Adjustment of thrust on obstacles and current - motor 2 [%] The control panel is fitted with a safety device which, when it detects an obstacle: - stops the opening movement and, if outside the limit area for detecting obstacles, performs a disengagement operation whose duration can be set with $\PP \to \mathbb{JE}$: - reverses the movement during closure operations outside the limit area for detecting obstacles; - stops the movement during closure operations within the limit area for detecting obstacles. The limit area for detecting obstacles during opening and closing is determined by the type of limit switch installed. If there is no limit switch, it is determined on the basis of the selections $\mathbb{J} P \to \mathbb{U}$ 0 - Minimum thrust 99 - Maximum thrust	See paragraph 11.2.1
	TR	TR - Motor delay time [s] Delay time for closure of gate wing 1 in relation to gate wing 2. 00-30 s	



NB: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

11.4.1 Additional BA level parameters that can be configured (available with Π T \to Π Π enabled)

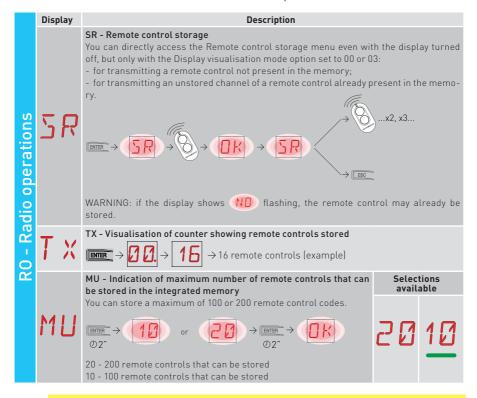
	Display	Description	Selections available
]] T	DT - Adjustment of obstacle recognition time [s/100] 10 - Minimum 60 - Maximum NB: the parameter is adjusted in hundredths of a second.	10,50
	5 T	ST - Adjustment of start time [s] 0.5 - Minimum 3.0 - Maximum	U.5,3.U
	TR	TA - Adjustment of acceleration time during opening [s] 0.5 - Minimum 9.9 - Maximum	5 9 9 9 9 9 9 9 9 9 9
	TQ	TQ - Adjustment of acceleration time during closure [s] 0.5 - Minimum 9.9 - Maximum	5.5 9.9 9. 9. 9. 9. 9. 9. 9
	111	VM - Initial movement speed [V] 00 - Minimum 15 - Maximum	See paragraph 11.2.1
	T』	TD - Adjustment of deceleration time [%] Adjusts the deceleration ramp slope 10 - Minimum 99 - Maximum	10,99
BA	03	OB - Setting of deceleration time during opening [s] Indicates the time between the start of the deceleration ramp and the end of the opening stroke 00 - Minimum 30 - Maximum	
		CB - Setting of deceleration time during closing [s] Indicates the time between the start of the deceleration ramp and the end of the opening stroke 00 - Minimum 30 - Maximum	0 G·3 0 10_
	PO	PO - Adjustment of approach speed during opening [V] Indicates the speed from the end of the deceleration ramp to the end of the opening stroke 03 - Minimum 10 - Maximum NB: gradually increase the approach speed if there is a series of quick vibrations (chattering) in heavy gates installed with a slight incline.	See paragraph 11.2.1
	PC	PC - Adjustment of approach speed during closing [V] Indicates the speed from the end of the deceleration ramp to the end of the closing stroke. 03 - Minimum 10 - Maximum	See paragraph 11.2.1
	00	00 - Obstacle detection limit during opening [%] Indicates the percentage of the distance travelled during $\Pi \to \Pi$ or after the detection of the opening limit switch $\Pi \to \Pi \to \Pi$ on which the disengagement is deactivated. NB: not active if $\Pi \to \Pi \to \Pi \to \Pi$.	05,99 29

ON - output always active



NB: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

11.5 Second level menu - RO (Radio Operations)



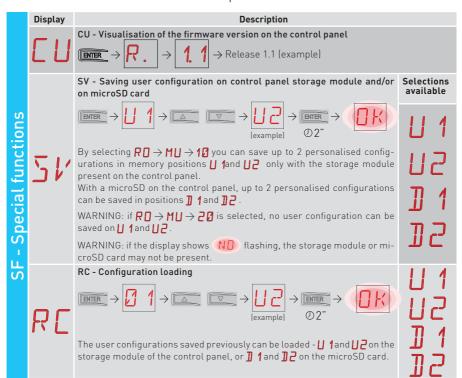


WARNING: selecting $M \sqcup \rightarrow 2 \mathcal{D}$ (200 remote controls), the configurations $\sqcup 1$ and $\sqcup 2$ saved with the $SF \rightarrow SV$ command will be lost. This also applies for the last configuration reloaded with RL. In addition, new configurations cannot be saved on $\sqcup 1$ and $\sqcup 2$.

11.5.1Additional RO level parameters that can be configured (available with $\Pi \to \Pi \Pi$ enabled)

Display	Description	Selections available	;
Display [1 2	C1, C2, C3, C4 - Selection of CH1, CH2, CH3, CH4 function of stored control. N0 - No setting selected 1-3 - Opening command 1-4 - Closing command 1-5 - Step-by-step command P3 - Partial opening command LG - Command to switch the courtesy light on/off 1-9 - STOP command If even just one (any) CH key of the remote control is stored, the opening by-step command is implemented. NB: the -	available remote or step- alterna-	034536
[4	If 2-4 CH keys of a single remote control are stored, the functions ma	tched in	

11.6 Second level menu - SF (Special Functions)



11.6.1Additional SF level parameters that can be configured (available with $\Pi \to \Pi \Pi$ enabled)

	Display	Description
		SP - Setting the password
	50	$\begin{array}{c} \text{ENTER} \rightarrow \boxed{?} 1 \\ \rightarrow \boxed{?} 2" \\ \end{array}$
	_ '	NB: this can only be selected when the password is not set. Setting the password prevents unauthorised personnel from accessing selections and adjustments. You can delete the set password by selecting the sequence JR1=0N, JR1=0FF, JR1=0N.
		IP - Inserting the password
	T P	$\boxed{\text{ENTER}} \rightarrow \boxed{1} \rightarrow \boxed{2} \qquad \rightarrow \boxed{1} $
SF	_	NB: this can only be selected when the password is set. When the password is not inserted, you can access the display mode regardless of the selection made with JR1. When the password is inserted, you can access in maintenance mode.
0)		EU - Deletion of user configurations and last configuration set in the storage module
	ЕШ	$ \begin{array}{c} \text{ENTER} \\ \text{© 2"} \end{array} $
	AL	AL - Alarm counter Used to view, in sequence, the counters of alarms that have been triggered at least once (alarm code + number of times triggered). With and you can scroll through all the counters and see all the alarms recorded.
		AH - Alarm log
	ЯН	Used to view, in sequence, alarms that have been triggered (maximum 20). With and vous can scroll through the entire alarm log. The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number (0) corresponds to the oldest alarm.

	Display	Description
	AR	AR - Alarm reset Resets all the alarms in the memory (counters and log).
	ЯE	AE - Writing of alarms on microSD card Creates a text file on the microSD memory, containing some information about the control panel: the firmware version, operation counters, hour counters, configuration parameters, alarms.
SF	ΕIJ	ED - Enabling of diagnostics Enables the periodic saving of data on the micro SD card, for diagnostic use. NO - Disabled 01 - Internal use (DO NOT USE) 02 - List of events on microSD card
	511	SU - Safe removal of the microSD card
	IM	 IM - Motor current visualisation Selecting M 1, the display will show the current absorbed by motor 1. Selecting M 2, the display will show the current absorbed by motor 2.
	UР	UP - Firmware update Activates the card bootloader in order to update the firmware. O 2"

11.7 Second level menu - CC (Cycles Counter)

	Display	Description
nter	C٧	CV - Display of total operations counter $ \begin{array}{c} $
7		CP - Display of partial operations counter
Cycles counte		
Š		CH - Display of power supply hour counter
0 - 00		
		BH - Visualisation of counter for power supply hours via battery
	BH	

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11.7.1 Additional CC level parameters that can be configured (available with $\Pi T \rightarrow \Pi \Pi$ enabled)

	Display	Description Selection availab	
	СA	CA - Setting the maintenance alarm (factory setting - alarm deactivated: 0.0 00.00). You can set the required number of operations (regarding the partial operations cour for signalling the maintenance alarm. When the set number of operations is reached, the alarm message appears on the dis V ②. Example: Setting the maintenance alarm after 700 operations (00) (07) (00) ■■ → □ → □ → □ → □ → □ → □ → □ → □ → □ →	
00	0 A	OA - Selecting maintenance alarm display mode 00 - Visualisation on display (alarm message	
	Z P	ZP - Reset of partial operations counter ①2" For correct functioning, you are advised to reset the partial operations counter: - after maintenance work; - after setting the maintenance alarm interval.	

11.8 Second level menu - EM (Energy Management)

Ħ	Display	Description	Select avail		
emer	Pľ	PV - Solar panel power supply (panels not supplied) ON - Enabled OF - Disabled			-
Energy management		ES - "Green Mode" (energy-saving) (disconnection of accessories of to terminals 0-1 when the automation is in standby) ON - Enabled (the red point on the right of the display flashes every 5 + LP-, -LK+ and 30-13 are not managed in low-consumption mod OF - Disabled	s. Outputs		,1
EM - Energ	E 5	Power supply disconnection mode is activated after 15 s with the gas or when the gate is idle and automatic closure is not enabled. The automation resumes its normal operation when a command is on the radio board (6ZENRS-ZENPRS) or following a contact 30-5, 30 or 30-4. WARNING: if you use accessories that need to remain powered Green Mode enabled (e.g. LAN4 or GOPAV), set the jumper AUX1-2 of the slot used on power supply 0-30.	s received 0-20, 30-3 even with	<u> </u>	-

11.8.1 Additional EM level parameters that can be configured (available with $\Pi T \rightarrow \Pi \Pi$ enabled)

	Display	Description	Selections available
	LL	LL - Voltage threshold for indicating that batteries are almost flat (V) 17 - Minimum 24 - Maximum NB: it is set with an interval of sensitivity of 0.5 V shown when the decimal point on the right lights up.	1724
EΜ	LB	LB - Indication that batteries are almost flat 00 - Visualisation on display (alarm message) 01 - Visualisation on flashing light (with the automation idle, 2 flashes ar and then repeated every hour) and on display (alarm message) 02 - Visualisation on "open gate" indicator light (with the automation clo flashes are made and then repeated every hour) and on display (alarm message)	\square 1
	BT	 BT - Battery mode 00 - Anti-panic (performs the opening operation following a mains su ure. The automation opens but does not accept any other comma the mains supply has been restored). 01 - Continuous operation - the last operation performed before contiswitch-off will be an opening. 02 - Continuous operation - the last operation performed before contiswitch-off will be an closure. 	rol panel

11.9 Second level menu - AP (Advanced Parameters)

		Display	Description	Select avail	
	ameters	FA	FA - Selection of opening limit switch mode NO - None SX - Stop limit switch (after activation, the gate wing stops its movement) PX - Proximity limit switch (after activation, the gate wing continues as far as the end stop and any obstacle is considered a stop) RA - Deceleration limit switch (after activation, the gate wing slows down its movement)	NO Px	
AP - Advanced parameters	avanced para	FC	FC - Selection of closing limit switch mode NO - None SX - Stop limit switch (after activation, the gate wing stops its movement) PX - Proximity limit switch (after activation, the gate wing continues as far as the end stop and any obstacle is considered a stop) RA - Deceleration limit switch (after activation, the gate wing slows down its movement)	NO Px	
	AP - Ac	16	D6 - Selection of device connected to terminals 1-6 N0 - None SE - Safety edge (if contact 1-6 opens, there is a disengagement of 10cm after the stop) S41 - Safety edge with safety test (if contact 1-6 opens, after the stop there is a disengagement of a duration depending on the selection	N 0 5 41 P 41	5 E P H

	Display	Description	Selections available
	18	D8 - Selection of device connected to terminals 1-8 NO - None SE - Safety edge S41 - Safety edge with safety test PH - Photocells P41 - Photocells with safety test	ND 5 E 5 41 P H P 41
ameters	R 9	R9 - Configuration of input 30-9 NO - Disabled 9P - The opening of the input causes a permanent stop 9T - The opening of the input causes a temporary stop. When the contact closes, the automatic closure time is activated (if enabled) HR - With the input open, the automation operates in "operator present" mode	NO9T 9PHR
AP - Advanced parameters	68	68 - Selection of the device simultaneously connected to terminals 1-6 and 1-8 NO - None SE - Safety edge S41 - Safety edge with safety test If different from NO, the simultaneous opening of inputs 1-6 and 1-8 causes: - movement stop and reversal during a closing operation - movement stop and disengagement of a duration depending on the selection P → JE during an opening operation	NO SE S41
	ΠS	DS - Setting of display visualisation mode 00 - No visualisation 01 - Commandsandsafetydeviceswithradiotest(seeparagraph 9.2) Display of countdown to automatic closing 02 - Automation status (see paragraph 13.1) 03 - Commands and safety devices (see paragraph 13.2)	00 01
	<u>L</u>	NB: the setting 1 allows you to see when a radio transmission is received, for range checks.	02 03



NB: make adjustments gradually and only after performing at least three complete operations to allow the control panel to be set correctly and detect any friction during operations.

11.9.1 Additional AP level parameters that can be configured (available with $\upbeta\ T \rightarrow \upbeta\ \Pi$ enabled)

	Display	Description	Selections available
	LL	LU - Setting the courtesy light switch-on time (s) To enable this parameter, set at least one of the selections → □ or □ → F as a courtesy light. It is set with different intervals of sensitivity. NO - Disabled - from 01" to 59" with intervals of 1 second - from 1' to 2' with intervals of 10 seconds - from 2' to 3' with intervals of 1 minute ON - Permanently enabled (switched off via remote control) NB: the courtesy light switches on at the start of each operation.	NO 0 159 1'
AP	L G	LG - Switch-on time for independently commanded courtesy light [s] To enable this parameter, set at least one of the selections	NO 0 159 1' - 2' 2' - 3' 0N
	b 1	PT - Fixed partial opening ON - Enabled OF - Disabled If ON, a partial opening command given on the partial opening position is ignored. With contact 30-20 closed (for example with the timer or manual selector), the gate will partially open. If it is then fully opened (command 30-3) and reclosed (even with automatic closing), it will stop at the partial opening position.	ON <u>OF</u>
	IJΕ	DE - Disengagement duration if an edge is triggered [s] Regulates the duration of the disengagement when an edge (active or passive) is triggered during opening or closure. In the case of gates with two wings, it acts on both wings. 00 - Deactivated	0.0 [,] 2.0
	JO	DO - Duration of disengagement on stop during opening [s/100] Regulates the duration of the disengagement on the mechanical opening stop. 00 - Disabled 99 - Maximum NB: not active if ► ↑ → 5 ×	00,99
	IC	DC - Duration of disengagement on stop during closure [s/100] Regulates the duration of the disengagement on the mechanical opening stop. 00 - Disabled 99 - Maximum NB: not active if	00,99

		Display	Description	Selections available
<u>а</u>		NE	WC - Setting of pre-flashing time on closing [s] Adjustment of the lead time for the switch-on of the flashing light, in relation to the start of the closing operation from a voluntary command. 00 - Minimum 05 - Maximum	0 0°0 5
Ā	⋖	T 5	TS - Setting of renewal of automatic closing time after safety device release [%] 00 - Minimum 99 - Maximum	00,99
		V R	VR - Setting of learning speed [V]	See paragraph 11.2.1

12. Diagnostics

12.1 Data Logging integrated in the board

The Entrematic LCU40H control panel is equipped with an internal system that allows the installer to check whether any alarms have been triggered, how many times, and the log of the last twenty alarms.

12.1.1 Alarm counter

With the third level menus enabled ($\Pi T \to \Pi \Pi$), go to $\Sigma F \to \Pi L$ to see all the alarms recorded by the control panel. The display alternately shows the alarm code and the number of times it was triggered.

Example: M0 _ 05 _ M0 _ 05 _

Use the and keys to scroll through the entire list of alarm counters.

12.1.2 Alarm log

With the third level menus enabled ($\Pi T \rightarrow \Pi \Pi$), go to $\Sigma F \rightarrow \Pi H$ to see the alarm log (the last 20 alarms recorded). The display shows the alarm number and code, alternated. The highest number corresponds to the most recent alarm and the lowest number corresponds to the oldest alarm.

Example: - 1 _ M0 _ - 1 _ M0 _

Use 🔼 and 🔽 to scroll through the alarm log.

With the third level menus enabled ($\mbox{\bf AT} \rightarrow \mbox{\bf AH}$), the microSD card inserted and the automation idle, go to $\mbox{\bf SF} \rightarrow \mbox{\bf AE}$ to export all the control panel parameters to the microSD. The LCU40H_INFO.txt text file created on the microSD contains all the alarm counters, the log showing the last twenty alarms, the operating statistics and the complete configuration of the control panel.

By inserting the microSD in a PC and opening the file LCU40H_INFO.txt with the Entrematic software, you can view all the control panel data.



NB: when the installation is complete, you are advised to delete the internal data logging.

12.2 Extended data logging on microSD

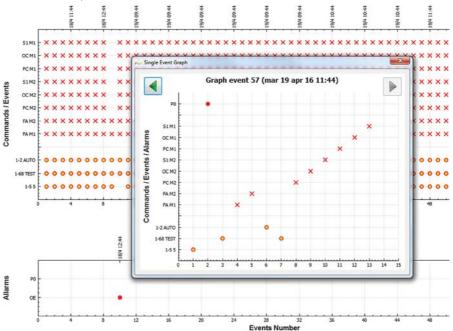
The Entrematic LCU40H control panel can record every event and/or alarm for every operation performed.

To do this, you must leave a microSD inserted in the relative connector and then, with the third level menus enabled $(AT \rightarrow AA)$, set $SF \rightarrow E \supset AC$.

In this way, at the end of every operation the control panel will save all the events recorded up to that moment on the microSD (in the LCU40H.log file in the LCU40H_ LOG folder).

You can view all the recorded logs by inserting the microSD in a PC and opening the LCU40H.log file using the Entrematic software.

This is an example of the visualisation of recorded events:



13. Signals visualised on the display

NB: depending on the type of automation and control panel, certain visualisations may not be available.

13.1 Display of automation status

NB: the automation status display mode is only visible with Display visualisation mode set to 02.



Display	Description	Display	Description
	Automation closed		Automation opening
-	Automation open] 1	Automation closing, from partial opening
	Automation stopped in intermediate position]:	Automation in partial opening
1 1	Automation closing]	Automation partially open

13.2 Display of safety devices and commands

NB: the safety device and command visualisation mode is only visible with Display visualisation mode set at 01 or 03.



Display	Description	Display	Description
1-2	1-2 - Automatic closing activation command	1-6	1-6 - Safety device with opening and closing stop
1-3	1-3 - Opening command	1-8	1-8 - Safety with closing reversal
1-4	1-4 - Closing command	1-9	1-9 - STOP command
1-5	1-5 - Step-by-step command	58	68 - Partial opening command

Display	Description	Display	Description
P 3	P3 - Partial opening command	52.	S2 Detection of stop during opening - motor 1
3P	3P - Opening command with operator present	5.2.	S.2 Detection of stop during opening - motor 2
46	4P - Closing command with operator present		00 Reaching of obstacle detection limit during opening - motor 1
RX	RX - Radio reception (of any memo- rised key of a transmitter present in the memory)	0.0.	0.0 Reaching of obstacle detection limit during opening - motor 2
N.L.V.	NX - Radio reception (of any non-mem- orised key)		OC Reaching of obstacle detection limit during closing - motor 1
NX	NB: with the selection $P \rightarrow 5 \rightarrow 6 \uparrow$ it is also visualised when a command is received from a non-stored transmitter.	Ο.Ε.	O.C Reaching of obstacle detection limit during closing - motor 2
EX	EX - Rolling-code radio reception out of sequence	RV	RV - Enabling/disabling of built-in radio receiver via RDX
EP	EP - Radio reception not complying with the parameter configuration \square \rightarrow \square	MQ	MQ - Learning operation of mechanical end stops in progress
EX	CX - Command received from AUX1 board	HT	HT - Heating of the motors (NIO function) in progress
EY	CY - Command received from AUX2 board	J 1	JR1 - Variation of the JR1 jumper status
F C.	FC Closure limit switch - motor 1	PE	PC - Recognition of connected HOST (Personal Computer)
F.C.	F.C Closure limit switch - motor 2	E 5	ES - Switch to Green Mode (energy-saving)
FA.	FA Opening limit switch - motor 1	1[1C - Closing operation (1 gate wing at a time)
F.A.	F.A Opening limit switch - motor 2	51	SD - Recognition of microSD card
5 1.	S1 Detection of stop during closure - motor 1	EI	ED - Log storage on microSD
5. 1.	S.1 Detection of stop during closure - motor 2		

WARNING: the visualisation of alarms and faults is possible with any visualisation selection. The signalling of alarm messages takes priority over all other displays.

Type of alarm	Display	Description	Operation
	MO	M0 - Automation type not selected	Select a type of automation from the $\mbox{\bf AT} \rightarrow \mbox{\bf AS}$ menu
	MH	M4 - Short circuit - motor 1	Check the connection of motor 1.
	M5	M5 - Short circuit - motor 2	Check the connection of motor 1.
	EM	MB - Absence of motor 1 during an operation	Check the connection of motor 1.
	ME	MC - Absence of motor 2 during an operation (if 2-motor functioning has been set)	Check the connection of motor 2.
	MI	MD - Irregular functioning of motor 1 opening limit switch	Check the connection of the motor 1 opening limit switch.
E	ME	ME - Irregular functioning of motor 1 closing limit switch	Check the connection of the motor 1 closing limit switch.
Mechanical alarm	MF	MF - Irregular functioning of motor 2 opening limit switch	Check the connection of the motor 2 opening limit switch.
Mechan	MG	MG - Irregular functioning of motor 2 closing limit switch	Check the connection of the motor 2 closing limit switch.
_	MH	MH - Door wing overlap not correct	Check that the motor which is the first to make the opening [M1] is connected as shown in fig. 1.
	MI	MI - Detection of third consecutive obstacle	Check for the presence of permanent obstacles along the stroke of the automation.
		OD - Obstacle during opening - gate wing 1	Check for the presence of obstacles along the automation stroke.
	OE	OE - Obstacle during closure - gate wing 1	Check for the presence of obstacles along the automation stroke.
	OF	OF - Obstacle during opening - gate wing 2	Check for the presence of obstacles along the automation stroke.
	06	OG - Obstacle during closure - gate wing 2	Check for the presence of obstacles along the automation stroke.
Settings alarm	56	S6 - Incorrect setting of safety device test	Check the configuration of parameters $16.19.69$. If $69 \rightarrow 541$, 16 and 18 cannot be 94 or 541 .
Service	V []	V0 - Request for maintenance intervention	Proceed with the scheduled maintenance intervention.

Type of

WD - Firmware reset not commanded

Type of alarm Display		Description	Operation
	R Ø	ing over 100 stored remote controls	To save the system configurations on the storage module, delete any stored remote controls and bring the total to less than 100. Set $R \square \rightarrow M \sqcup \rightarrow 1 \square$.
Radio operations alarm	R3	R3 - Storage module not detected	Insert a storage module.
io operat	RH	R4 - Storage module not compatible with the control panel	Insert a compatible storage module.
Rad	R5	R5 - No serial communication with the storage module	Replace the storage module.
	R5	R6 - Insertion of a specific storage module for testing	
Power supply alarm	PØ	P0 - No mains voltage	Check the control panel is powered correctly. Check the line fuse. Check the mains power supply.
Powe	P 1	P1 - Microswitch voltage too low	Check the control panel is powered correctly.
Battery	BØ	B0 - Battery almost flat	Check battery voltage. Replace battery.
	A Ø	A0 - Failure of test of safety sensor on contact 6	Check the device SOFA1-A2 is working correctly. If the supplementary SOF board is not inserted, check the safety test is disabled.
	R 1	A1 - Simultaneous safety sensor test on contacts 6 and 8 failed	Check the wiring and correct operation of the safety sensor.
s alarm	R 3	A3 - Failure of test of safety sensor on contact 8	Check the device SOFA1-A2 is working correctly. If the supplementary SOF board is not inserted, check the safety test is disabled.
Accessories alarm	R7	A7 - Incorrect connection of contact 9 to terminal 41	Check that terminal 1 and 9 are correctly connected.
Ac	89	A9 - Overload on output +LP-	Check the device connected to output +LP- is working properly.
	A B	AB - Overload on output 30-13	Check the device connected to output 30-13 is working properly.
	RG	AG - Alarm for short-circuit on output -LK+	Check the device connected to output -LK+ is working properly.

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14. Troubleshooting

Problem	Possible cause		n sig- ling	Operation
The control panel does not switch on	control panel No power supply. not switch on		Check the power supply cable and the relative wiring	
	Overload on output 0-30			Disconnect any loads connected to terminal 30
The automation does not open or	No power.			Check power supply cable.
close.	Short-circuited accessories	I5		Disconnect all accessories from terminals 0-30 (a voltage of 24V= must be present), then reconnect them one at a time. Contact Technical Service
	Blown line fuse.			Replace fuse.
	Safety contacts are open.	1-6 68	1-8	Check that the safety contacts are closed correctly (NC).
	Safety contacts not correctly connected or self-controlled safety edge not functioning correctly.	A0 A1 A3	1-6 1-8 68	Check connections to terminals 6-8 on control panel and connections to the self-controlled safety edge.
	Photocells activated.	1-6	1-8	Check that the photocells are clean and operating correctly.
	The automatic closure does not work.			Issue any command. If the problem persists, contact Technical Service
	Motor fault	M B M C		Check motor connection, if the problem persists, contact Technical Service.
The external safety devices are not activated.	Incorrect connections between the photocells and the control panel.	n. MI		Check that I- 5 / I- B is displayed Connect NC safety contacts together in series and remove any jumpers on the control panel terminal board.
				Check the $\mbox{\it HP} \rightarrow \mbox{\it J6}$ and $\mbox{\it HP} \rightarrow \mbox{\it J8}$ setting
The automation opens/closes briefly and then stops.	There is a presence of friction.			Manually check that the automation moves freely and check the 1/12 adjustment. Make sure that any limit switches, if present, are working correctly. Contact Technical Service
The remote control has limited range and does not work with the auto-				Install the antenna outside. Replace the transmitter batteries.
mation moving. The remote control does not work				Switch the automation off and plug in the
udes not Work	rect storage module.	R R		correct storage module.
	RS		Check the correct memorisation of the transmitters on the built-in radio. If there is a fault with the radio receiver that is built into the control panel, the remote control codes can be read by removing the storage module.	

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